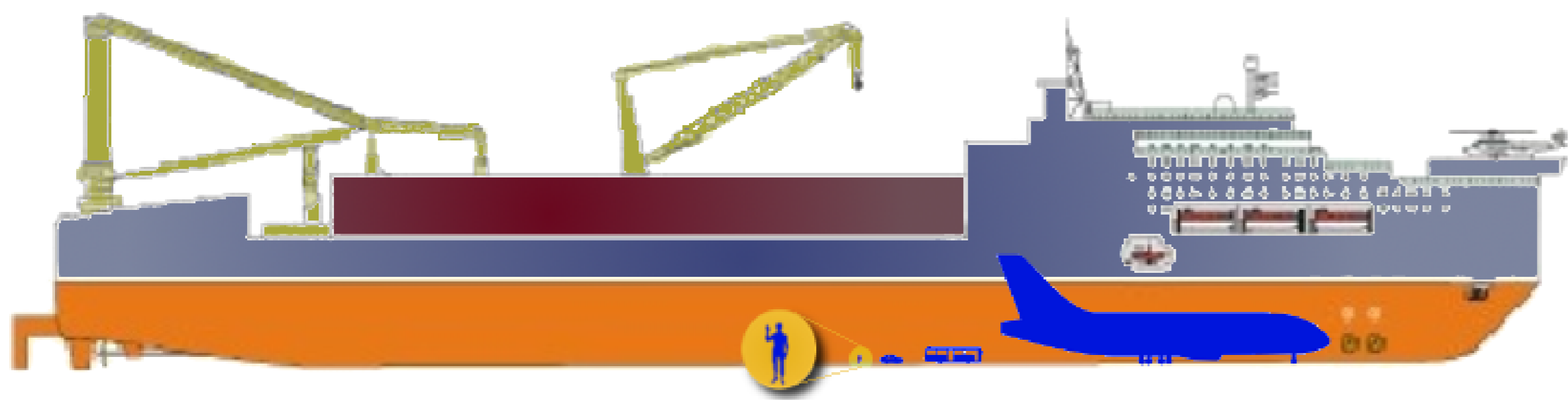


## THE VESSEL: CASTOR ONE

Castor One targets the large gas trunklines and oil export pipelines, in difficult environments, deepwater and arctic conditions



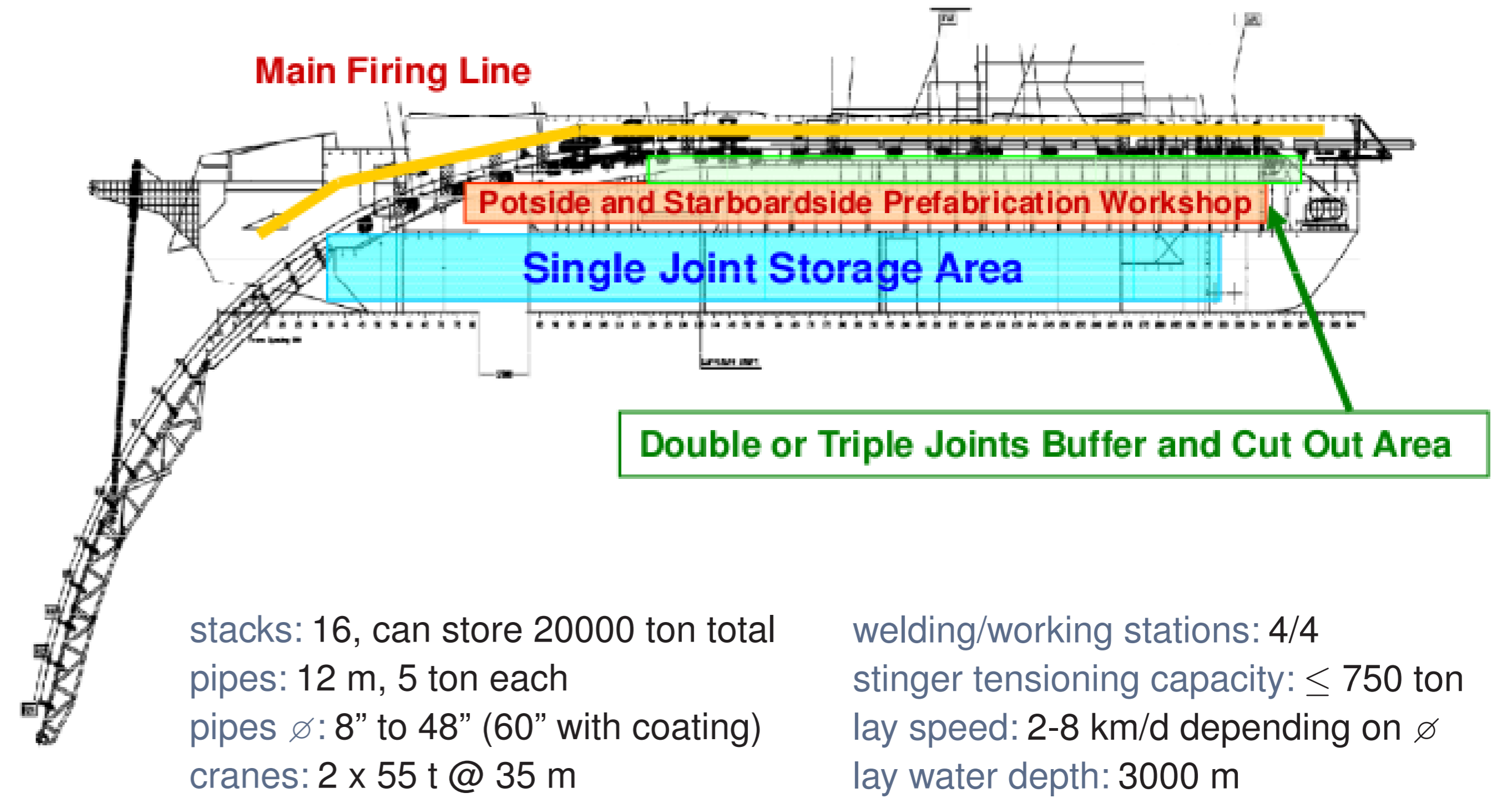
### Main particulars



constructor: ENI/Saipem  
construction year: 2012  
L/W/H: 330 m / 40 m / 67 m  
displacement: 100000 ton  
max speed: 14 knots (26 km/h)  
accommodation: 702 persons

main gensets: 8 x 8,400 kW at 600 rpm each  
emergency generator: 1 x 1,200 kW  
power distribution: 2 switchboards 11 kV  
bow tunnel/azimuthal thrusters: 2 x 35 t / 6 x 92 t  
main shafts: 2 x 8,000 kW

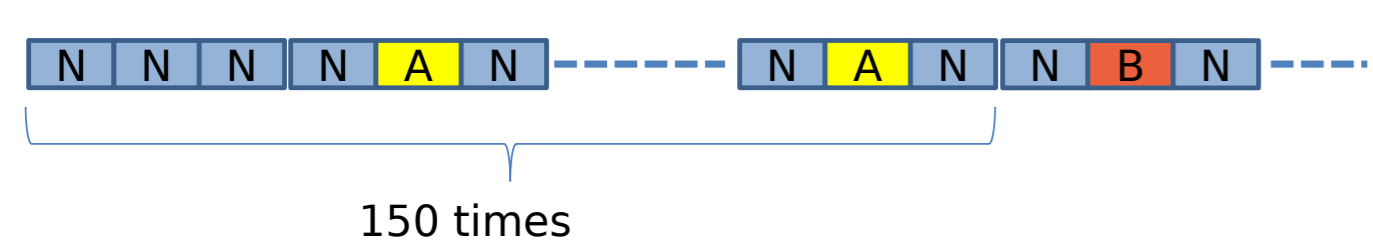
## Pipe Storage and Production Capacity



## THE CHALLENGE

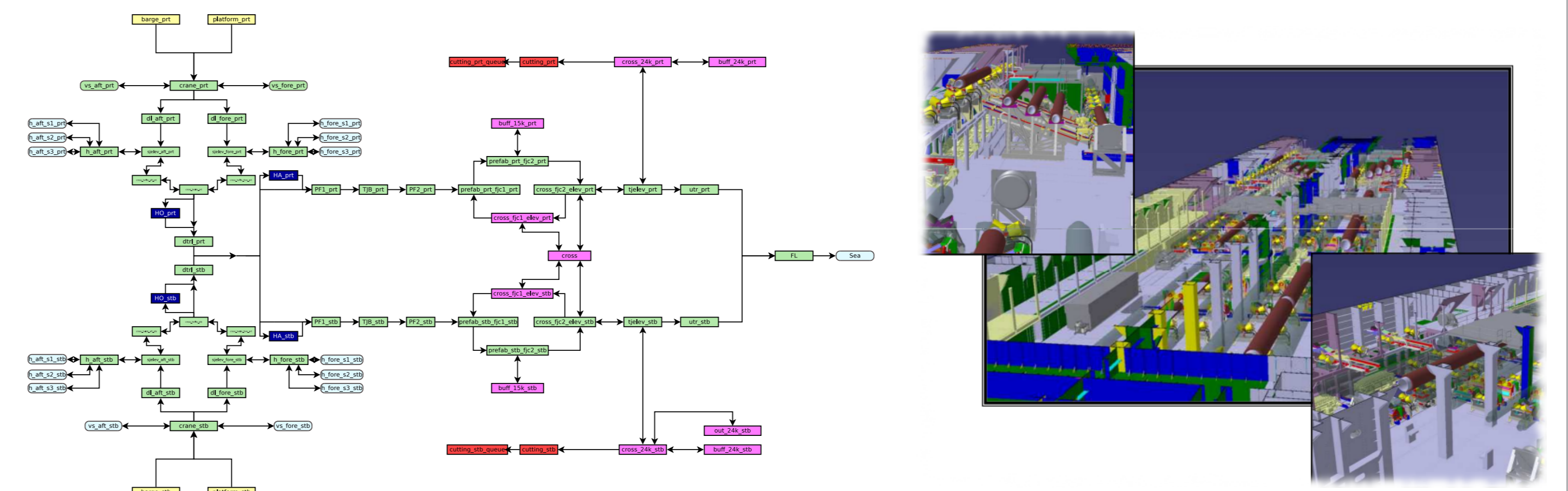
### The Vessel's Goals

- ▶ The Vessel must produce and laid a *precise sequence of pipes*.
  - ▷ Firing Sequence (FS): The precise sequence of pipes
  - ▷ Each pipe in FS has a type (e.g. A, B, N) and a section ( $\varnothing$ )
- ▶ The FS must be achieved while respecting some constraints, policies and other secondary goals.
  - ▷ Some plants machinery can be disabled
  - ▷ Load balancing of prefabrications
  - ▷ Vessel's weight balancing must be kept
  - ▷ Distribution of pipe's types
  - ▷ Safety thresholds for provisioning
  - ▷ Vessel autonomy
  - ▷ Optimize pipes provisioning
  - ▷ ...



### Vessel's Plant, Work Process and Pipe Provisioning

- ▶ Single Pipes (SJs) are taken from holds and carried to the two prefabrications
- ▶ In prefabrication triplets of SJs are welded into Triple Joints (TJs)
- ▶ TJs are then sent to the Firing Line for being welded to the final FS and laid into the sea
- ▶ Stacks are refilled by Barges (pipe carrier vessels)



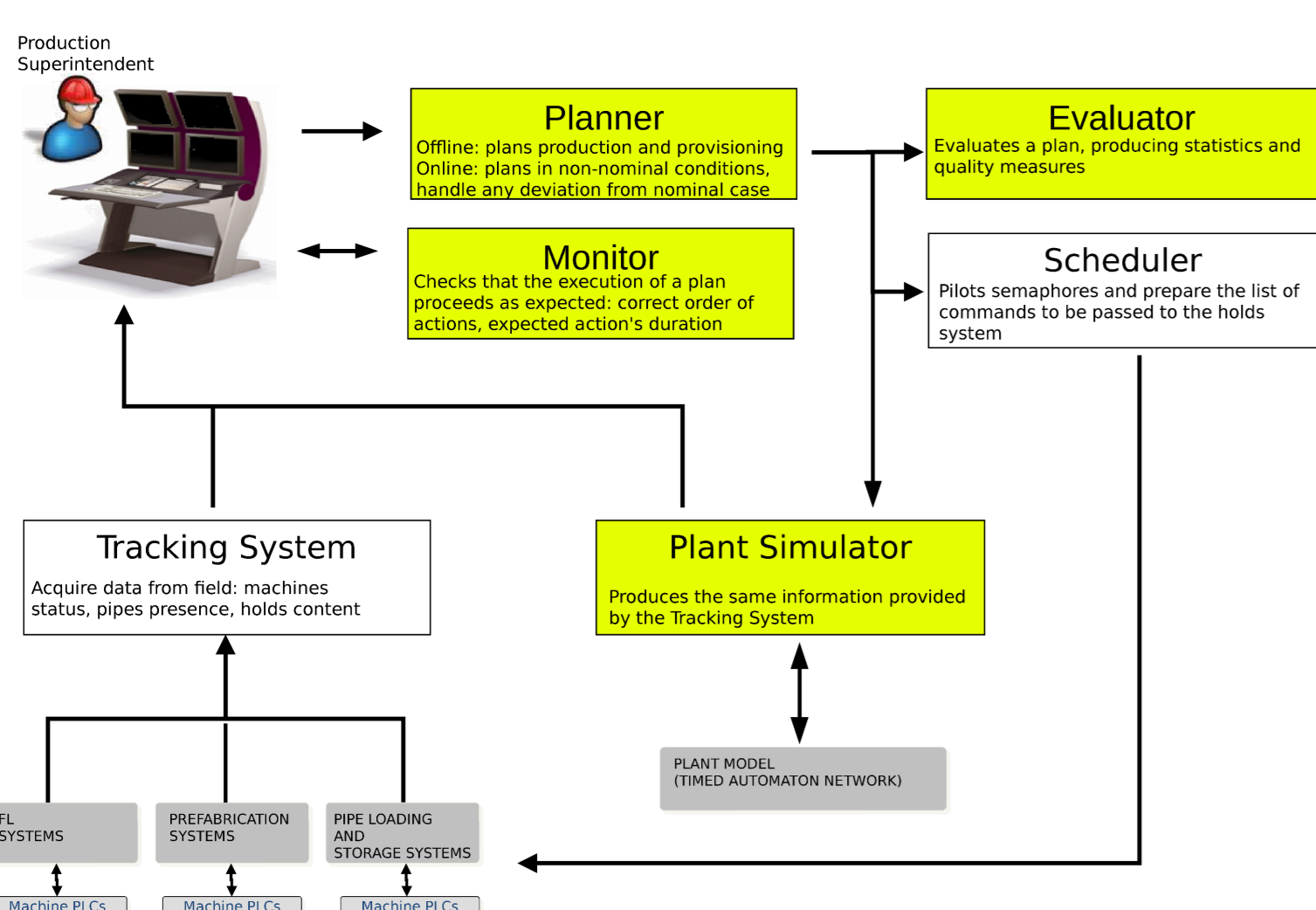
### Faults Happen!

- ▶ Faults can happen both at plant level and pipe level
- ▶ Noticeably, pipes are in a row and their order can be changed only exploiting a limited number of buffers
- ▶ When a fault happens, faulty pipes shall be sent to the cutting stations, faulty paths shall be avoided, and the FS must be achieved taking care of remaining pipes in the plant, and re-arranging provisioning

## THE PLANNING & MONITORING SYSTEM

The Planning System is built on top of low-level hold handling and hardware level.

- ▶ Used both as Engineering Tool and for Live Operations
- ▶ Physical Plant can be substituted by a Simulator
- ▶ Features a Human-Machine Interface in the Control Room
- ▶ Produced plans can be sent to the Simulator, or to the physical plant through the Scheduler



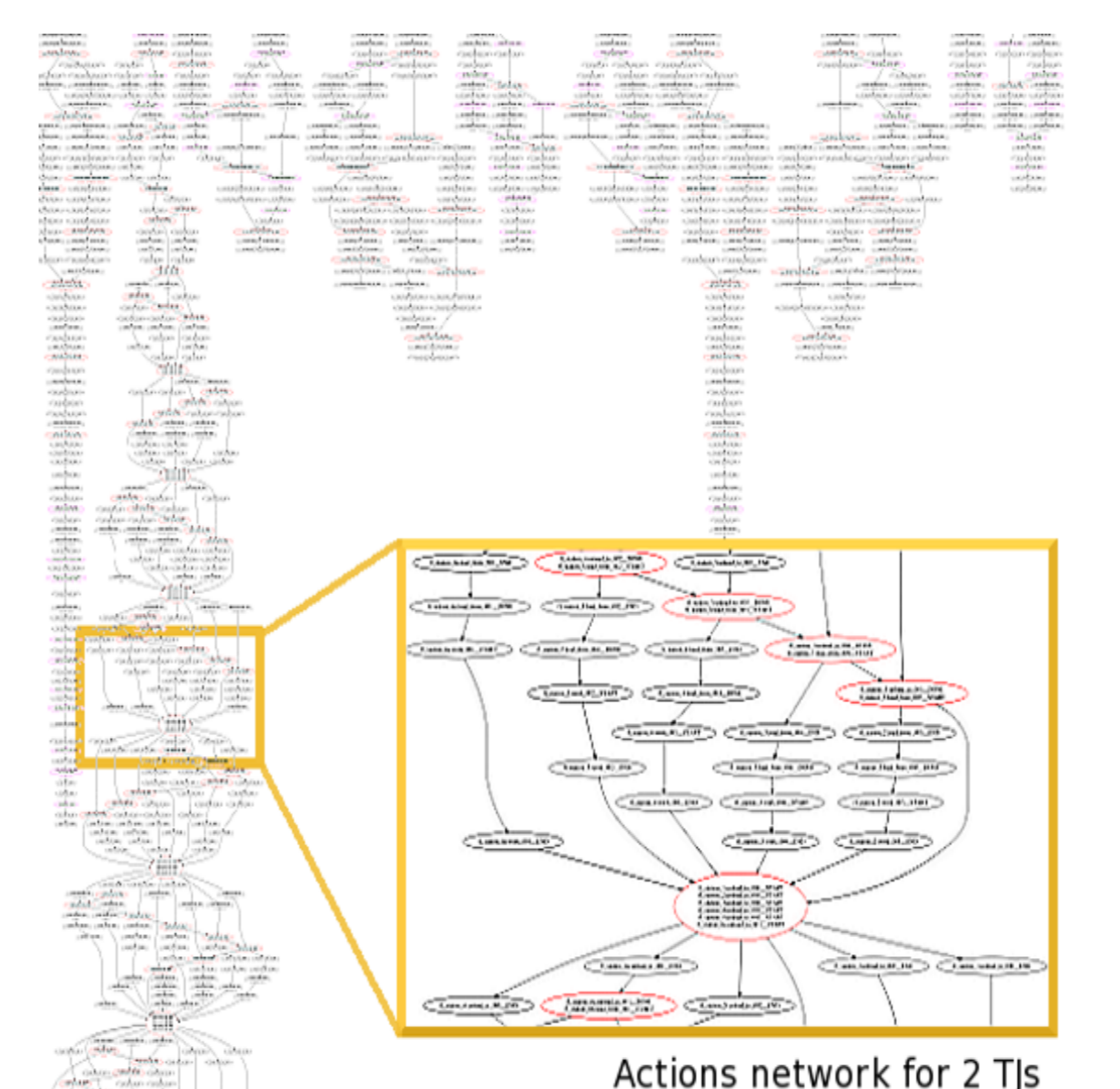
### The Planner

- ▶ Generates a *production plan*
  - Planner Model
  - Planner to tactical mapping
  - Constraints Policies
  - plant status
  - plan frontier
  - Planner
  - plan
  - Plan Expander
  - tactical plan
  - barge manifest
- ▶ When faults happen, *re-plans* to achieve the goals with the new plant condition
  - ▷ When re-planning with *patching*: try keeping minimal deviation from the previous plan

The planner is made of two search engines:

- ▶ A graph-based A\* heuristics planner for production planning and re-planning
- ▶ The provisioning planner
  - ▷ Genetic search: for large, loosely constrained problems
  - ▷ BFS search: for small, highly constrained problems

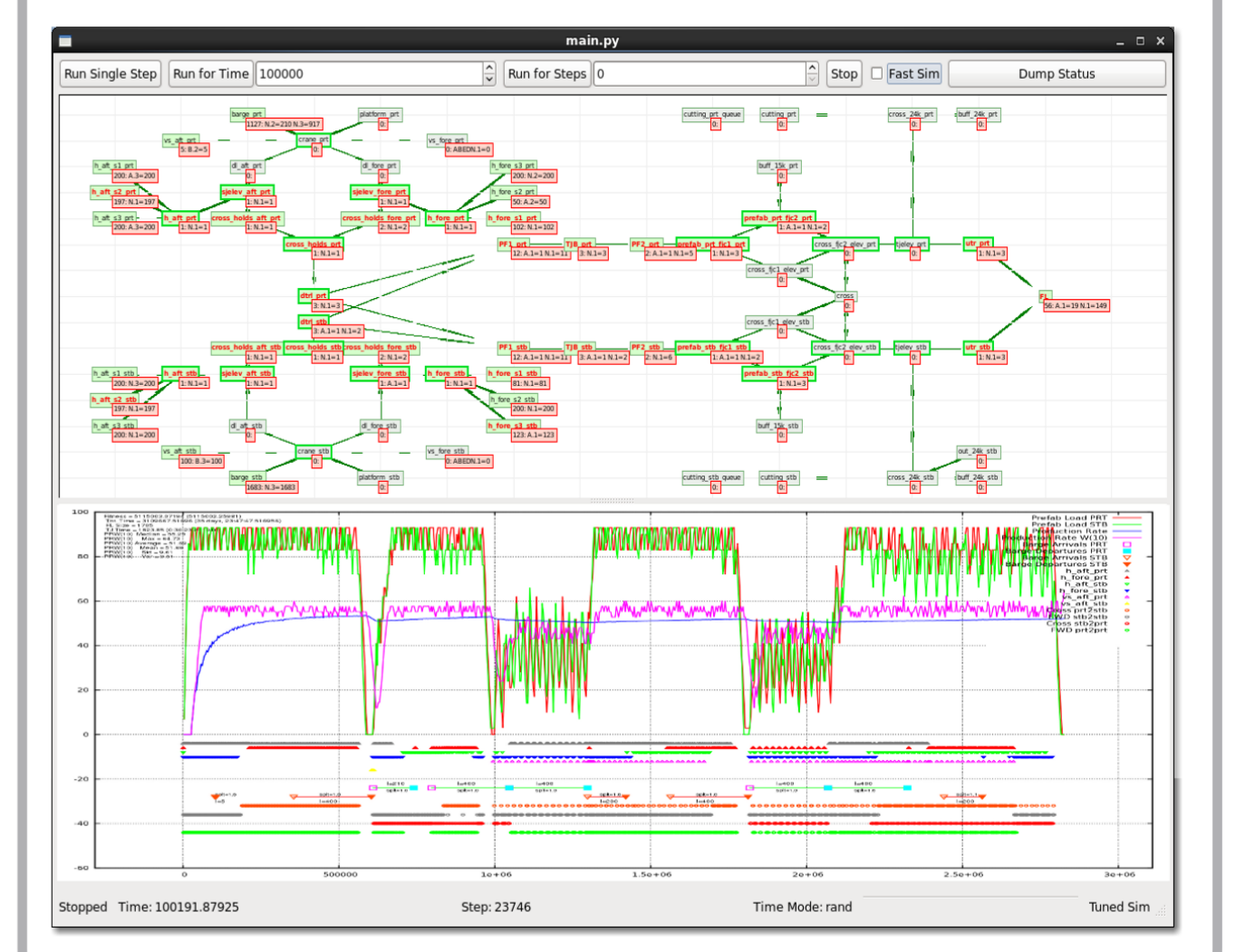
### The Monitor



- ▶ A graph containing duration and dependency order of actions
- ▶ Monitor is notified as the actions are executed:
  - ▷ Checks action's durations against the graph
  - ▷ Checks action's orderings against the graph

### The Plan Evaluator

- Produces statistics and quality measures out of the execution of a plan  
Examples of important measures are:
- ▶ Production Rate (pipes/day)
  - ▶ Load Balancing
  - ▶ Working timings
  - ▶ Barges number and balancing
  - ▶ ...



### The Simulator

- ▶ Simulates a Network of Timed Automaton abstracting the Physical Plant
- ▶ It is used when Planning System is used as Engineering Tool, i.e. for plan debugging and what-if analysis
- ▶ Noticeably, the Planning System interfaces indifferently with the Simulator or with the Physical Plant